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Ultrasonic Assisted Drilling

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Motivation

- Drilling ductile materials forms large burrs
- Burrs affect quality of parts and assembly
- Deburring is expensive
- Ultrasonic assisted drilling alter the machining process to reduce burr size



Topics of Discussion

- Burr Formation
- Ultrasonic Assisted Drilling
- Actuated Workpiece Holder Design
- Drive Circuit Design
- Experimental Investigation
- Conclusion

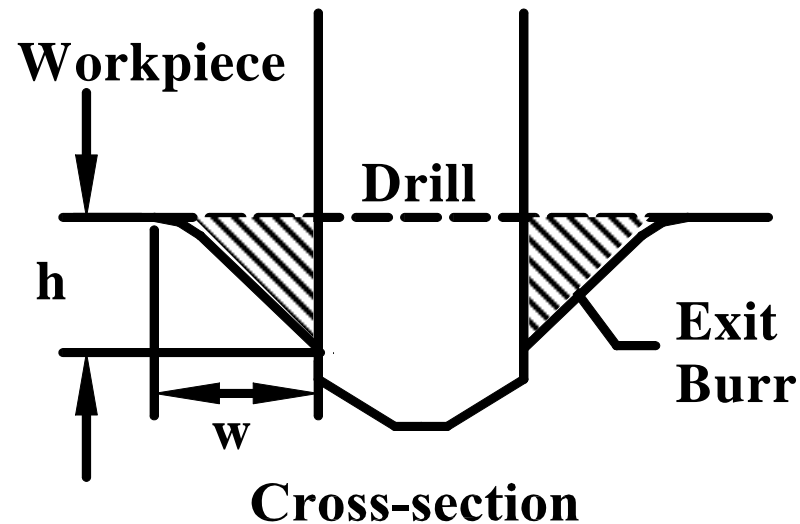


Burr Formation

- Undesirable projection of work material
- Result from plastic deformation
- Poisson Burr, Entrance Burr, Rollover Burr, Tear Burr, Cutoff Burr
- Drilling forms combination of Rollover Burr and Tear Burr at the exit surface

Burr Formation

- Exit burr size is defined by the height and the width





Ultrasonic Assisted Drilling

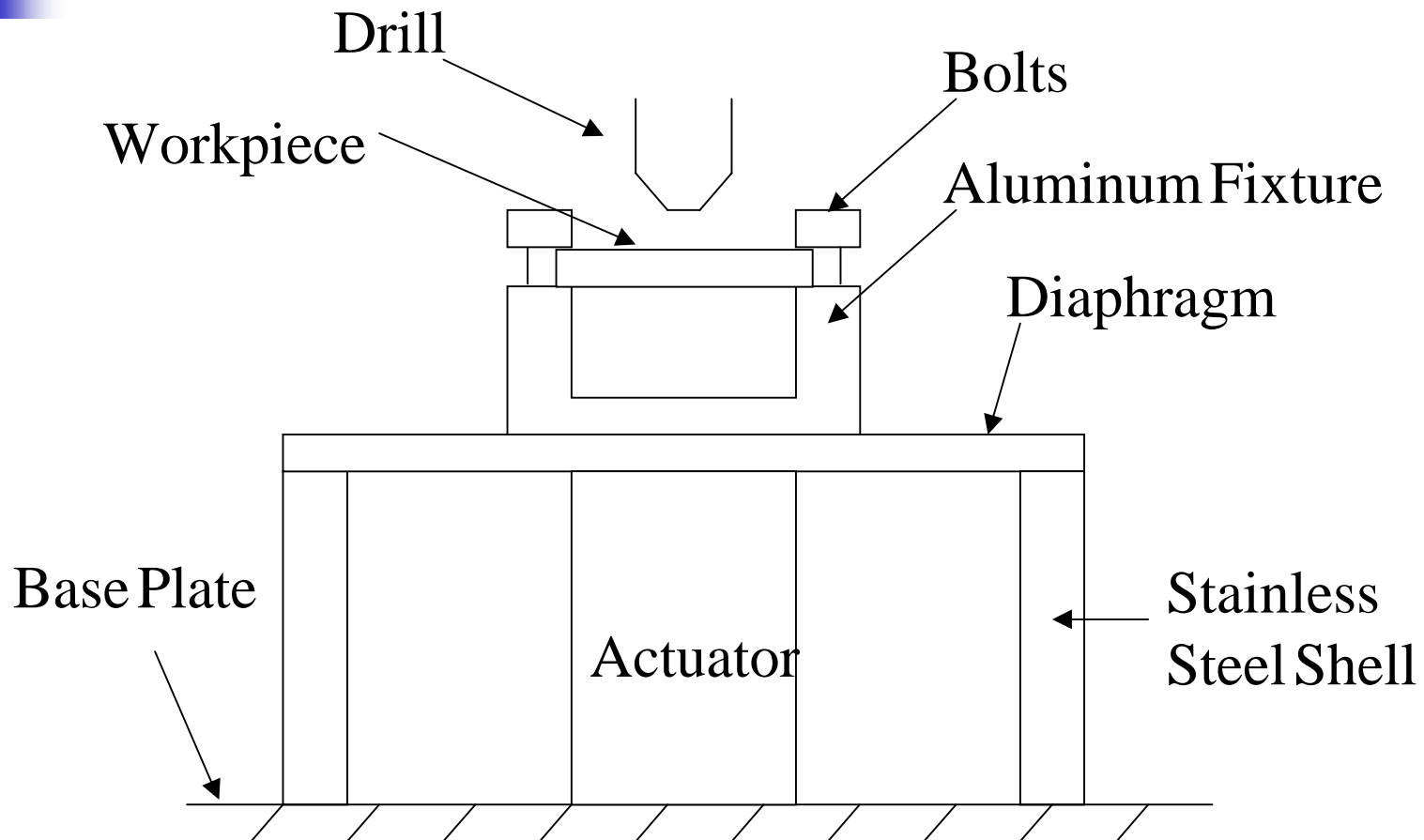
- Adding high frequency and low amplitude vibration in the direction of drill feed
- High Frequency – 1 - 200kHz
- Low Amplitude – 1 - 13 μ m

Actuated Workpiece Holder design



- Piezoelectric stack actuator
- Pre-loading mechanism
- Aluminum fixture
- Stainless steel shell
- Base plate

Actuated Workpiece Holder design



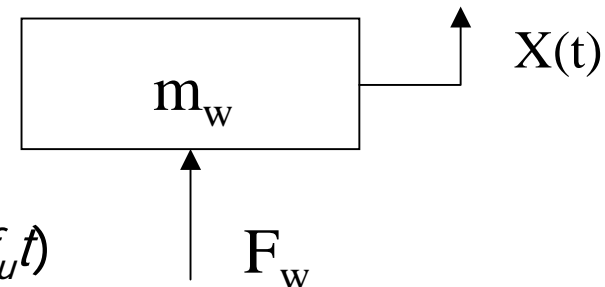
Actuated Workpiece Holder design

- Desired actuator performance:

- Freq. Range 0-20kHz
- Disp. Range 0-10 μ m

- Required force delivery

- $X(t) = A_u \sin(2\pi f_u t)$
- $V(t) = 2\pi f_u A_u \cos(2\pi f_u t)$
- $a(t) = -4\pi^2 f_u^2 A_u \sin(2\pi f_u t)$
- $F_w(t) = -4\pi^2 f_u^2 A_u m_w \sin(2\pi f_u t)$
- $F_{max} = 4\pi^2 f_u^2 A_u m_w = 8 \text{ kN}$



Actuated Workpiece Holder design



- Chosen actuator
 - Sensor Tech. Ltd. BM532 series 33 layers stack actuator
 - Freq. Range 0-20kHz
 - Disp. Range 0-4 μ m
 - Force Delivery 5kN
 - Applied Voltage (V_a) 200V
 - Capacitance (C) 290nF

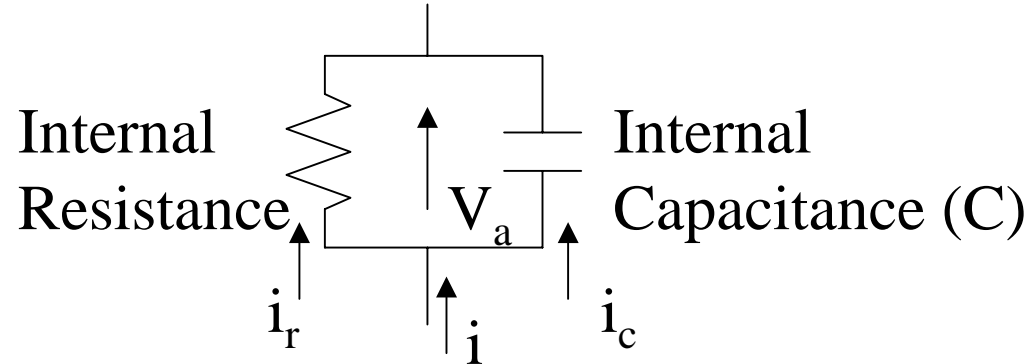


Drive Circuit Design

- Operating frequency 20kHz
- Required 200V pk-pk drive voltage
- Required drive current can be computed by considering the electric model of the actuator

Drive Circuit Design

- Electric model of the actuator



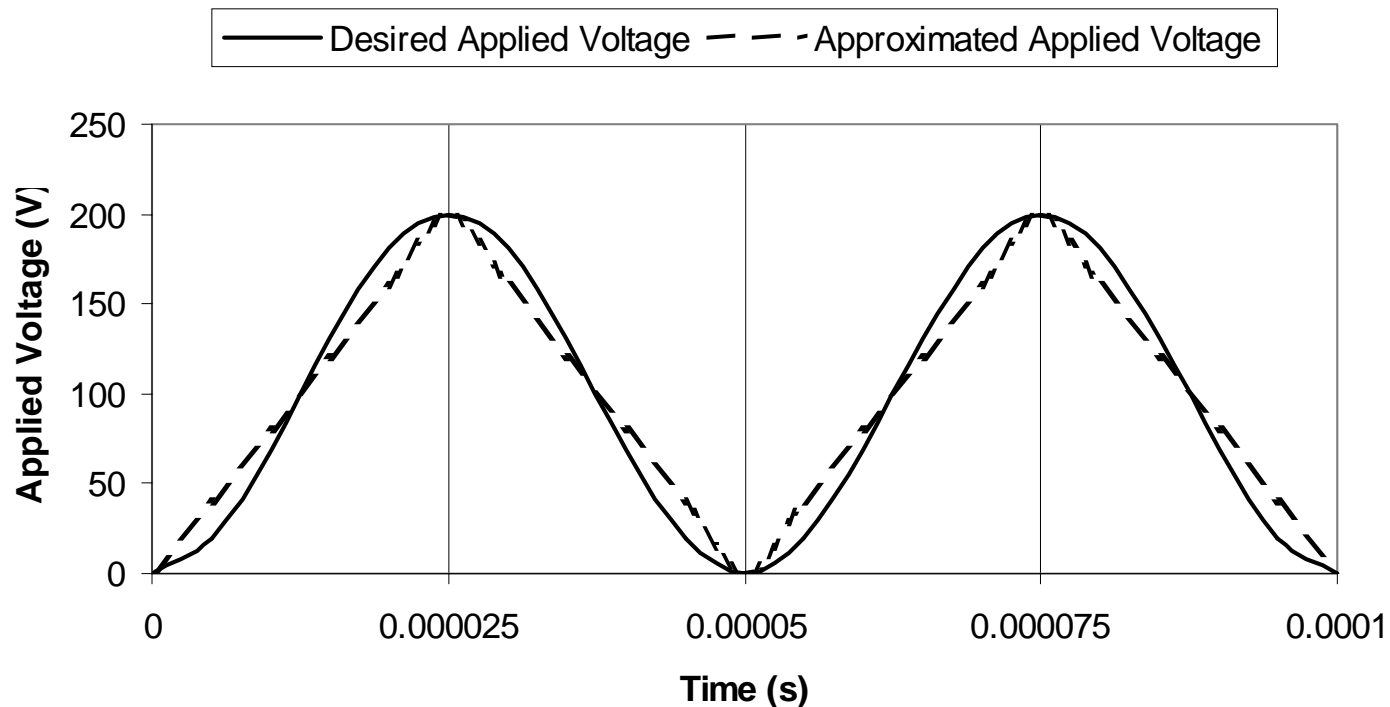
- Required charging current can be computed using the relation:

$$C \frac{dV_a}{dt} = i_c$$

Drive Circuit Design

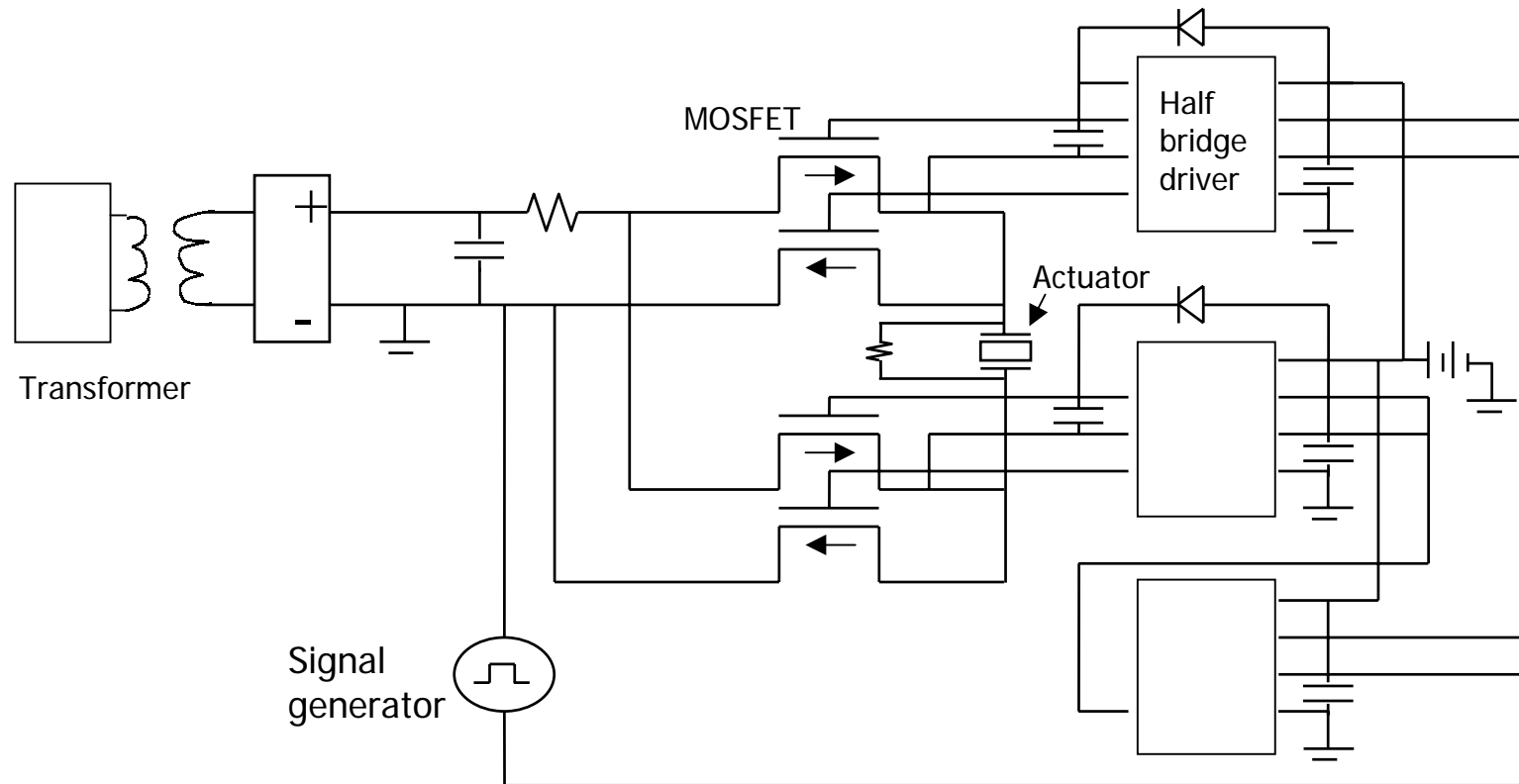
- Required charging current = 2.3A

Actuator's Voltage vs Time



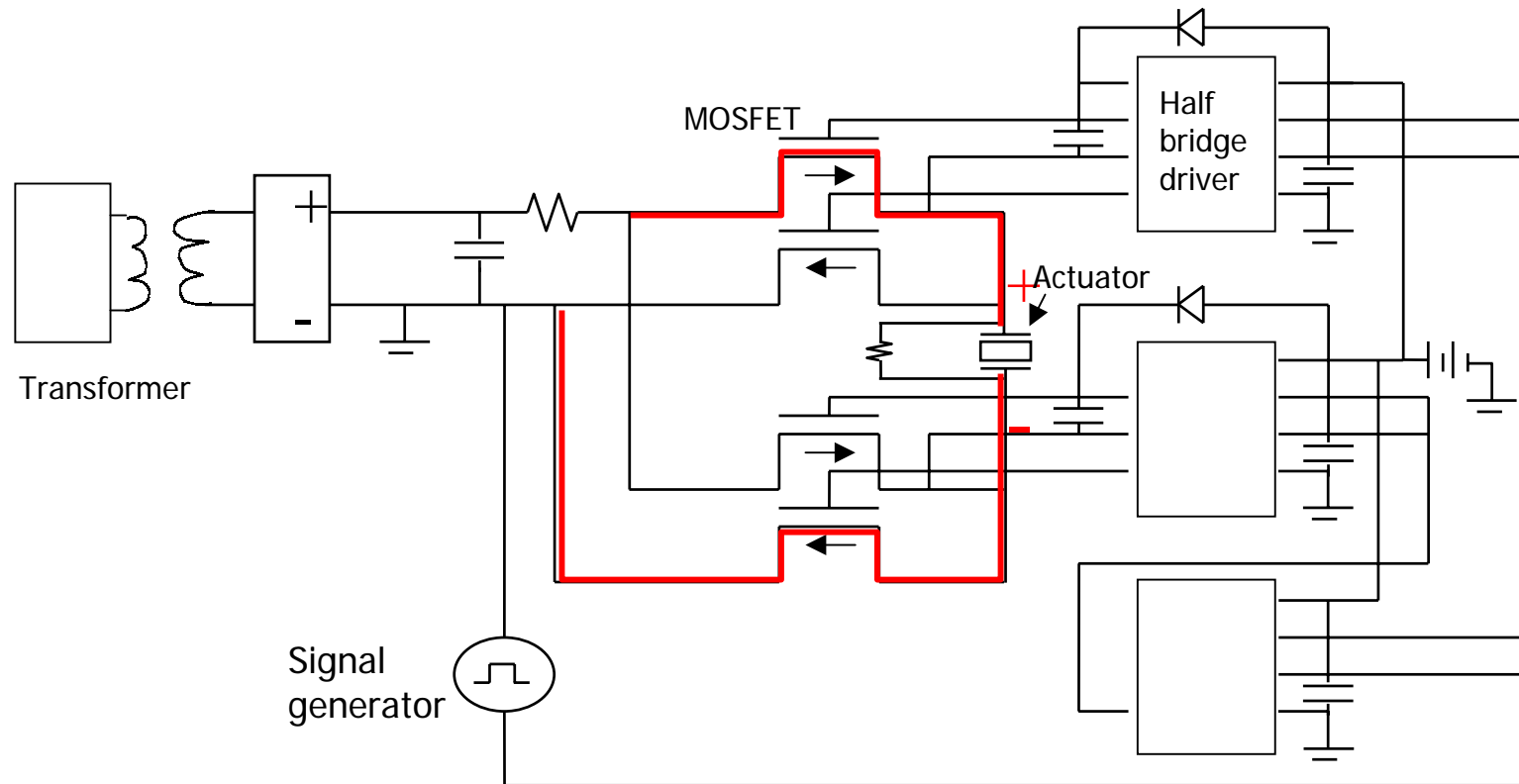
Drive Circuit Design

■ Polarity Switching Circuit



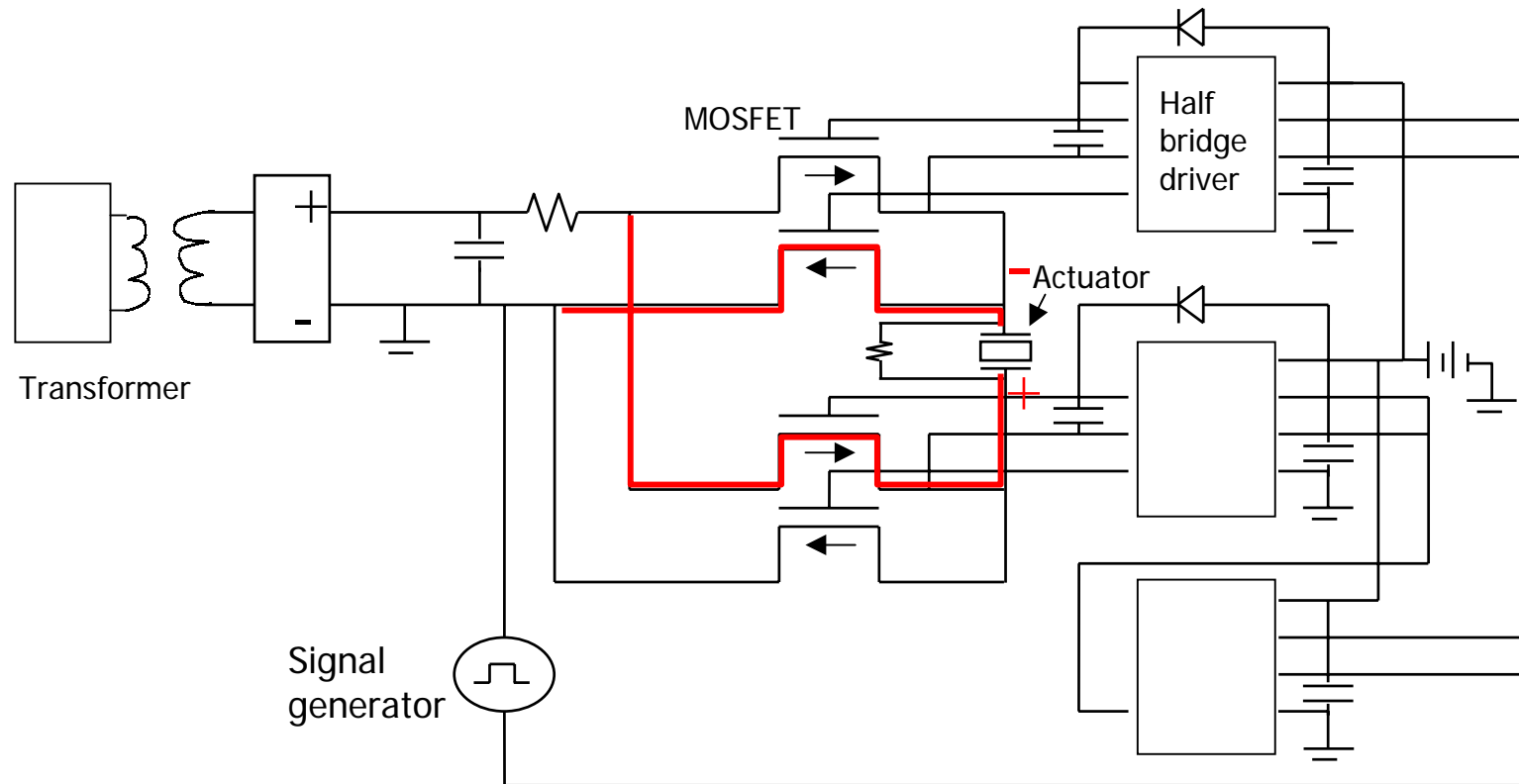
Drive Circuit Design

■ Polarity Switching Circuit



Drive Circuit Design

■ Polarity Switching Circuit





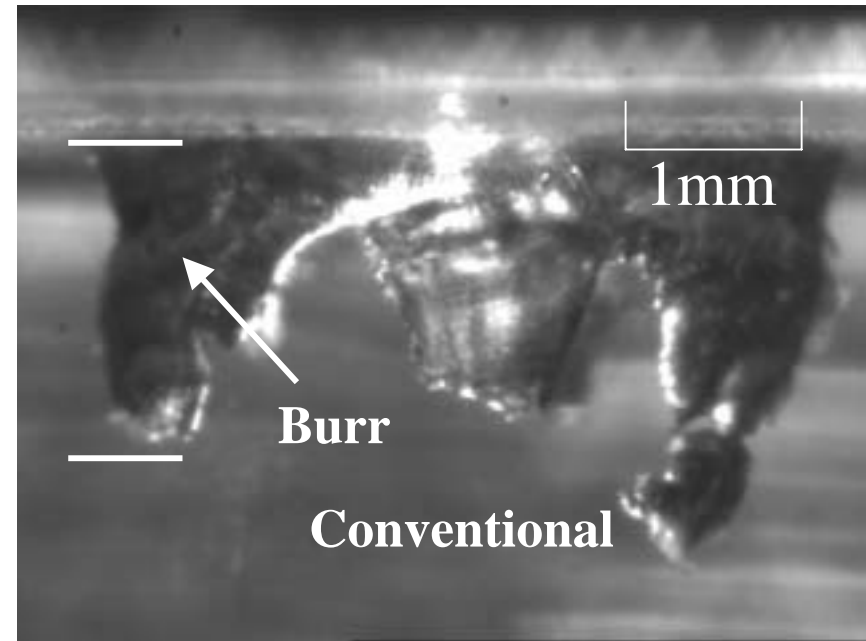
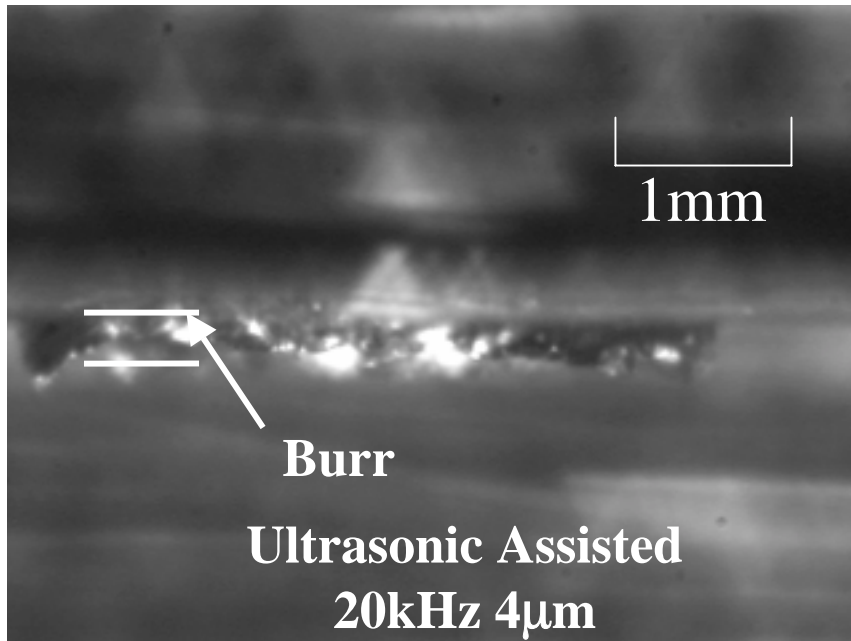
Experimental Investigation

- Experimental Setup
 - CNC milling machine
 - 5 specimen for each test
 - New finished High Speed Steel twist drill
 - Burr height measured under scaled microscope
 - Burr width measured by vernier caliper

Experimental Investigation

- Example of samples

3.175mm drill 6000RPM 1.905mm/s feed





Experimental Investigation

- Vibration Frequency
- Peak to Peak Vibration
- Spindle Speed
- Other Findings
- Tool Wear

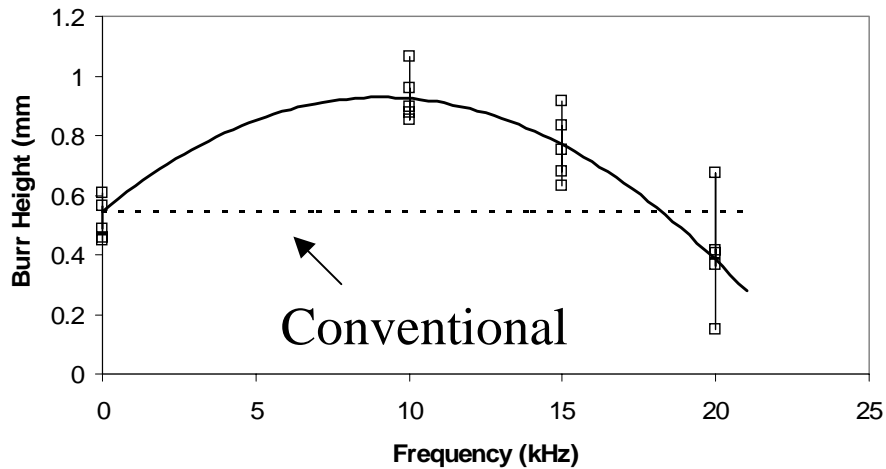


Vibration Frequency

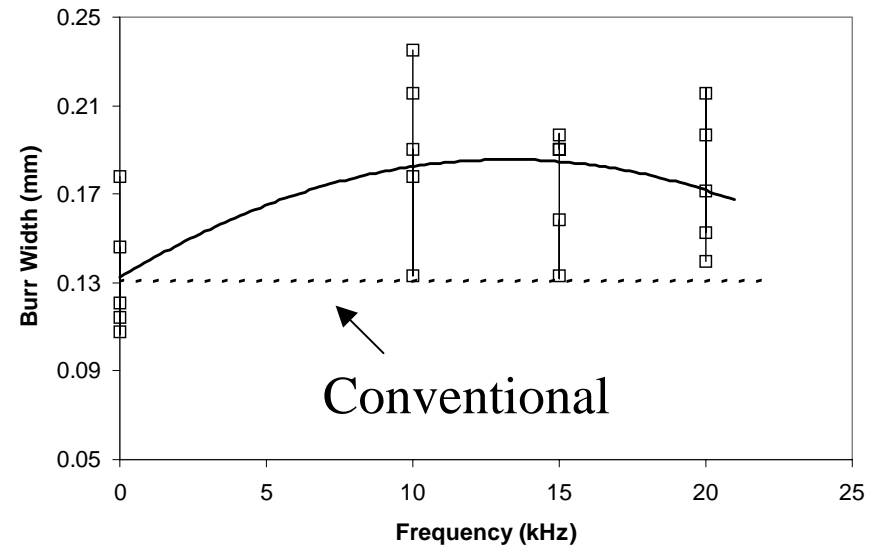
- Burr height and width decreased after the frequency reaches a threshold
- Trends suggested higher frequency results in smaller burr
- Wavy chips were found at low frequency tests

Vibration Frequency

Burr Height vs Vibration Frequency (Test # 1, 2, 5, 6)
(3.18mm Drill 4000RPM 1.90mm/s feed 4microns vibration)

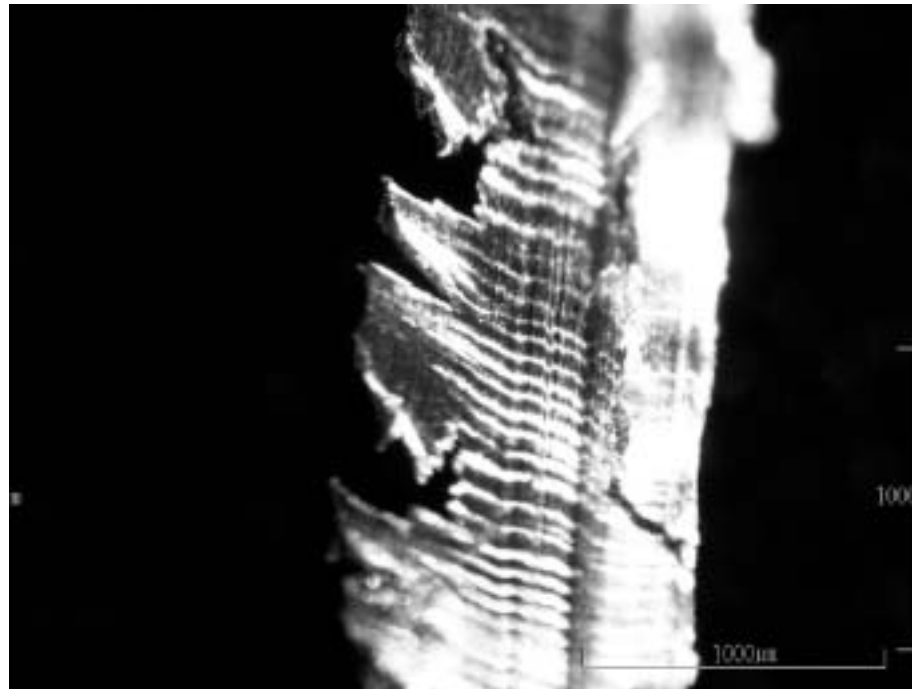


Burr Width vs Vibration Frequency (Test # 1, 2, 5, 6)
(3.18mm Drill 4000RPM 1.90mm/s feed 4microns vibration)



Vibration Frequency

- Wavy chip





Vibration Frequency

- Continuous cutting occurs at lower frequencies, forming long wavy chips
- Ultrasonic impact action occurs at higher frequencies, segmenting the chips, forming fine chips

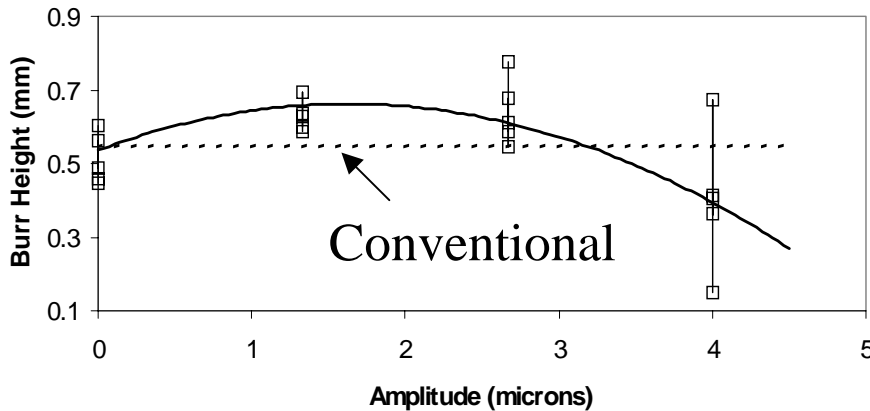
Peak to Peak Vibration Magnitude



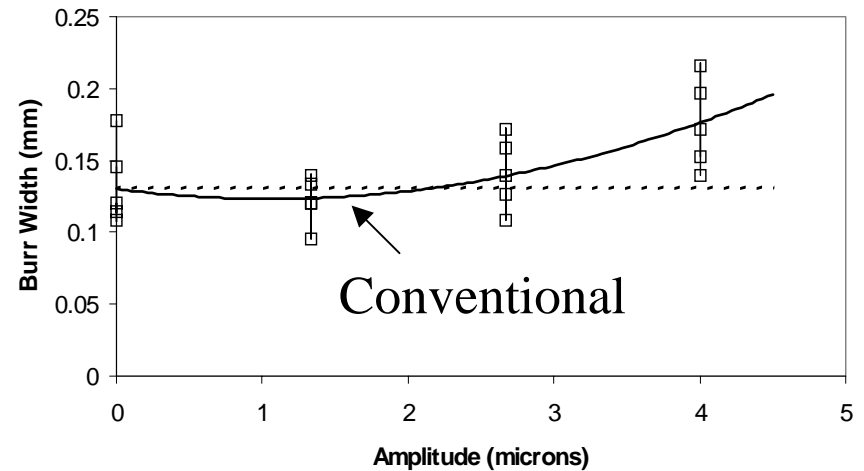
- Burr height decreased but burr width increased after the magnitude reaches a threshold

Peak to Peak Vibration Magnitude

Burr Height vs Vibration Amplitude (Test # 1, 2, 3, 4)
 (3.18mm Drill 4000RPM 1.90mm/s feed 20kHz frequency)



Burr Width vs Vibration Amplitude (Test # 1, 2, 3, 4)
 (3.18mm Drill 4000RPM 1.90mm/s feed 20kHz frequency)



Peak-to-peak Vibration Magnitude



- Continuous cutting occurs at lower magnitudes, forming long wavy chip
- Ultrasonic impact action dominates at higher magnitudes
 - Rollover begins earlier
 - Forms short but wide burrs

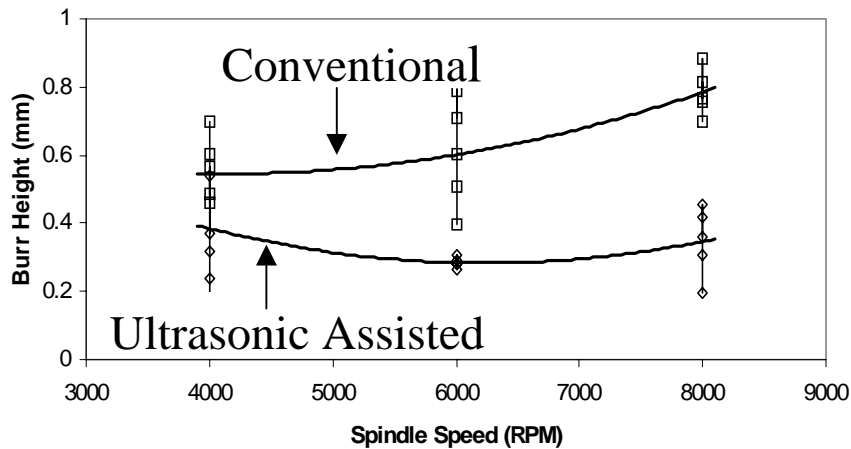


Spindle Speed

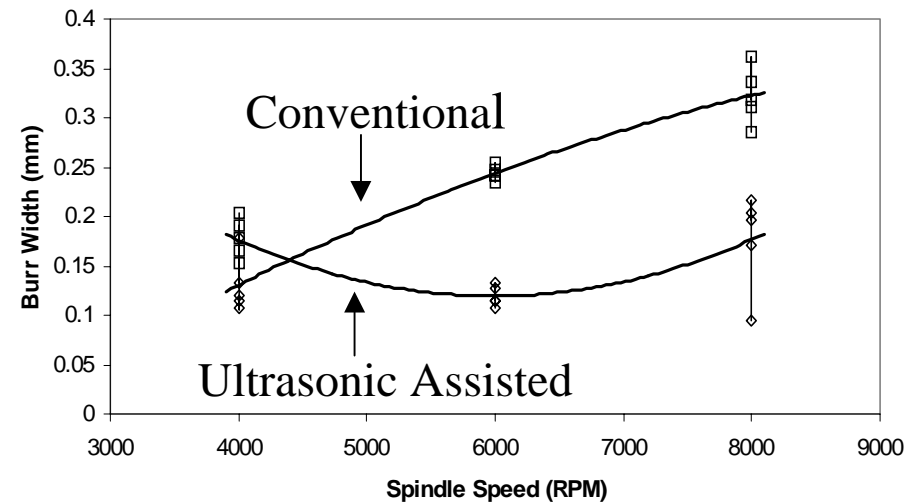
- Both burr height and width reaches a minimum at 6000rpm, and significantly smaller than conventional drilling at 6000 and 8000rpm.
- Trends suggested a certain vibration condition can significantly reduce burr size

Spindle Speed

Burr Height vs Spindle Speed (Test # 1, 2, 13, 14, 15, 16)
 (3.175mm Drill 1.905mm/s feed vibration condition: 20kHz 4microns)



Burr Width vs Spindle Speed (Test # 1, 2, 13, 14, 15, 16)
 (3.175mm Drill 1.905mm/s feed vibration condition: 20kHz 4microns)





Effect of Spindle Speed

- Higher spindle speed with same feed results in thinner chips that are broken more easily by the ultrasonic impact action, producing smaller burr



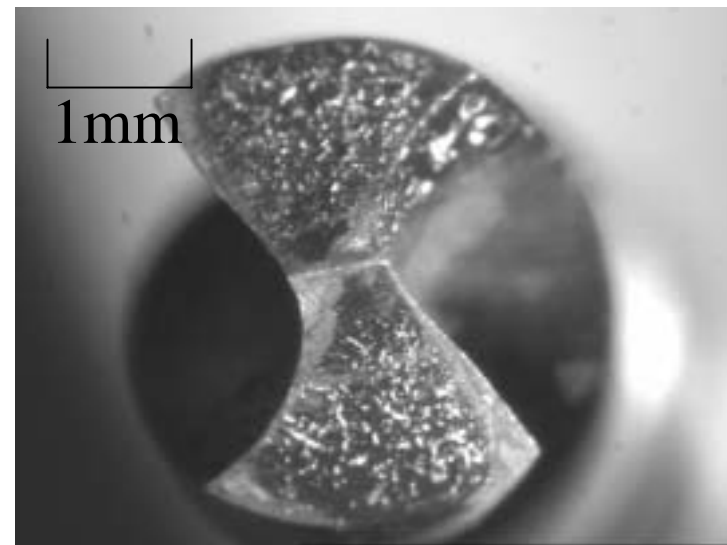
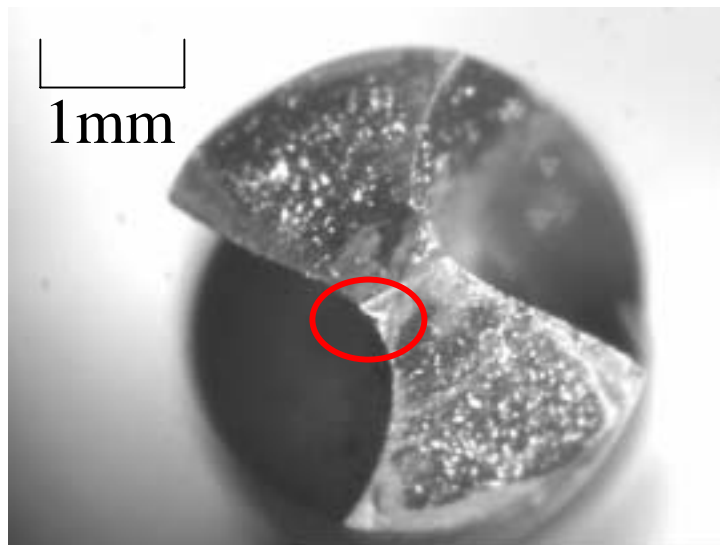
Other Findings

- Ultrasonic assisted drilling performs best in normal cutting feed, but degrades rapidly in high cutting feed
- Drill size has insignificant effect on the efficiency of ultrasonic assisted drilling

Effect of Ultrasonic Assistance in Tool Wear

- Chipping observed on drills used in ultrasonic assisted drilling experiment

8000RPM, 3.81mm/s feed (left: UA; right: conventional)





Conclusion

- Ultrasonic assisted drilling in general:
 - Reduces burr height and width if the vibration conditions for each particular cutting condition were chosen correctly
 - Introduces challenges in the context of tool strength and tool life